Chapter 4

The Richardson Iteration

Definition 4.1 Richardson iteration. Let $\mathbf{x}^{(0)} \in \mathbb{R}^n$ be a given initial iterate. The Richardson¹ iteration for computing a sequence of vectors $\mathbf{x}^{(k)} \in \mathbb{R}^n, k = 0, 1, 2, \ldots$, has the form

$$\mathbf{r}^{(k)} = \mathbf{b} - A\mathbf{x}^{(k)}, \quad \mathbf{x}^{(k+1)} = \mathbf{x}^{(k)} + \alpha_k \mathbf{r}^{(k)}$$
(4.1)

with appropriately chosen numbers $\alpha_k \in \mathbb{R}$.

Definition 4.2 Co-domain of a matrix. The set

$$\mathcal{R}\left(A
ight) = \left\{rac{\mathbf{y}^{*}A\mathbf{y}}{\mathbf{y}^{*}\mathbf{y}} : \mathbf{y} \in \mathbb{C}^{n}, \mathbf{y} \neq \mathbf{0}
ight\} \subset \mathbb{C}$$

is called co-domain of A.

Remark 4.3 On the co-domain of a matrix. The co-domain of A is the co-domain of the unit sphere of \mathbb{C}^n since

$$\frac{\mathbf{y}^* A \mathbf{y}}{\mathbf{y}^* \mathbf{y}} = \frac{\mathbf{y}^* A \mathbf{y}}{\|\mathbf{y}^*\|_2 \|\mathbf{y}\|_2} = \underbrace{\frac{\mathbf{y}^*}{\|\mathbf{y}^*\|_2}}_{\|\cdot\|_2 = 1} A \underbrace{\frac{\mathbf{y}}{\|\mathbf{y}\|_2}}_{\|\cdot\|_2 = 1}.$$

The unit sphere is a compact set (bounded and closed) and the mapping $\mathbf{y} \mapsto \mathbf{y}^* A \mathbf{y} / \mathbf{y}^* \mathbf{y}$ is continuous. It follows that $\mathcal{R}(A)$ is also a compact set. \Box

Lemma 4.4 Co-domain of the inverse matrix. Let $A \in \mathbb{R}^{n \times n}$ with $\mathcal{R}(A) \subset \{\lambda \in \mathbb{C} : Re(\lambda) > 0\}$, i.e., the co-domain of A is a subset of the right half of the complex plane. Then

$$\mathcal{R}(A^{-1}) \subset \{\lambda \in \mathbb{C} : Re(\lambda) > 0\}.$$

Proof: From the assumption it follows that A is non-singular. Otherwise, there would be a vector $\mathbf{z} \in \ker(A)$, $\mathbf{z} \neq \mathbf{0}$, and

$$\operatorname{Re}\left(\frac{\mathbf{z}^{*} \stackrel{=0}{A\mathbf{z}}}{\mathbf{z}^{*}\mathbf{z}}\right) = \operatorname{Re}\left(0\right) = 0.$$

This contradicts the assumption on $\mathcal{R}(A)$.

¹Lewis Fry Richardson (1881 – 1953)

Let $\mathbf{y} \in \mathbb{C}^n$, $\mathbf{y} \neq \mathbf{0}$, be arbitrary and $\mathbf{z} = A^{-1}\mathbf{y} \neq \mathbf{0}$. Hence, \mathbf{z} is also an arbitrary vector. One has

$$\operatorname{Re}\left(\frac{\mathbf{y}^{*}A^{-1}\mathbf{y}}{\underbrace{\mathbf{y}^{*}\mathbf{y}}_{\in\mathbb{R}}}\right) = \frac{1}{\|\mathbf{y}\|_{2}^{2}}\operatorname{Re}\left(\mathbf{y}^{*}A^{-1}\mathbf{y}\right) = \frac{1}{\|A\mathbf{z}\|_{2}^{2}}\operatorname{Re}\left((A\mathbf{z})^{*}\underbrace{A^{-1}A}_{=I}\mathbf{z}\right)$$
$$= \frac{1}{\|A\mathbf{z}\|_{2}^{2}}\operatorname{Re}\left(\mathbf{z}^{*}A^{*}\mathbf{z}\right) = \frac{1}{\|A\mathbf{z}\|_{2}^{2}}\operatorname{Re}\left(\left(\mathbf{z}^{*}A^{*}\mathbf{z}\right)^{*}\right) = \frac{1}{\|A\mathbf{z}\|_{2}^{2}}\operatorname{Re}\left(\mathbf{z}^{*}A\mathbf{z}\right)$$
$$= \frac{\|\mathbf{z}\|_{2}^{2}}{\|A\mathbf{z}\|_{2}^{2}}\operatorname{Re}\left(\frac{\mathbf{z}^{*}A\mathbf{z}}{\mathbf{z}^{*}\mathbf{z}}\right) \ge \frac{1}{\|A\|_{2}^{2}}\operatorname{Re}\left(\frac{\mathbf{z}^{*}A\mathbf{z}}{\mathbf{z}^{*}\mathbf{z}}\right) > 0,$$

where $\|A\mathbf{z}\|_2 \le \|A\|_2 \|\mathbf{z}\|_2$ has been used.

Theorem 4.5 Convergence of the Richardson iteration. Let $A \in \mathbb{R}^{n \times n}$ with $\mathcal{R}(A) \subset \{\lambda \in \mathbb{C} : Re(\lambda) > 0\}$. Then the Richardson iteration (4.1) converges to the solution of the linear system $A\mathbf{x} = \mathbf{b}$ for every initial iterate if $\alpha_k = \alpha$, $k = 0, 1, 2, \ldots$, with

$$0 < \alpha < \min\{\beta = \operatorname{Re}(\lambda), \ \lambda \in \mathcal{R}(A^{-1})\}$$

Proof: Note that $\mathcal{R}(A^{-1})$ is a compact set such that the minimum exists. Let **x** be the solution of (1.1). It will be shown that the error $\left\|\mathbf{x} - \mathbf{x}^{(k)}\right\|_2$ decreases strongly monotonically and the rate of decrease is strictly lower than one. Using $\mathbf{b} = A\mathbf{x}$ and (4.1), one has the recursion

$$\mathbf{x} - \mathbf{x}^{(k+1)} = \mathbf{x} - \mathbf{x}^{(k)} - \alpha \mathbf{r}^{(k)} = \mathbf{x} - \mathbf{x}^{(k)} - \alpha \left(\mathbf{b} - A\mathbf{x}^{(k)}\right)$$
$$= \mathbf{x} - \mathbf{x}^{(k)} - \alpha A\left(\mathbf{x} - \mathbf{x}^{(k)}\right).$$

Hence,

$$\begin{aligned} \left\| \mathbf{x} - \mathbf{x}^{(k+1)} \right\|_{2}^{2} &= \left(\mathbf{x} - \mathbf{x}^{(k)} - \alpha A \left(\mathbf{x} - \mathbf{x}^{(k)} \right), \mathbf{x} - \mathbf{x}^{(k)} - \alpha A \left(\mathbf{x} - \mathbf{x}^{(k)} \right) \right) \tag{4.2} \\ &= \left\| \mathbf{x} - \mathbf{x}^{(k)} \right\|_{2}^{2} - 2\alpha \left(\mathbf{x} - \mathbf{x}^{(k)} \right)^{T} A \left(\mathbf{x} - \mathbf{x}^{(k)} \right) + \alpha^{2} \left\| A \left(\mathbf{x} - \mathbf{x}^{(k)} \right) \right\|_{2}^{2}. \end{aligned}$$

 $\subseteq \mathbb{R}$

Denoting $\mathbf{y} = A\left(\mathbf{x} - \mathbf{x}^{(k)}\right)$, one obtains

$$\frac{\left(\mathbf{x} - \mathbf{x}^{(k)}\right)^{T} A\left(\mathbf{x} - \mathbf{x}^{(k)}\right)}{\|A\left(\mathbf{x} - \mathbf{x}^{(k)}\right)\|_{2}^{2}} = \frac{\left(\mathbf{x} - \mathbf{x}^{(k)}\right)^{T} A^{T} A^{-T} A\left(\mathbf{x} - \mathbf{x}^{(k)}\right)}{\|A\left(\mathbf{x} - \mathbf{x}^{(k)}\right)\|_{2}^{2}} = \frac{\mathbf{y}^{T} A^{-T} \mathbf{y}}{\mathbf{y}^{T} \mathbf{y}}$$

$$= \frac{\mathbf{y}^{T} A^{-1} \mathbf{y}}{\mathbf{y}^{T} \mathbf{y}} \geq \min\left\{\operatorname{Re}(\lambda) : \lambda \in \mathcal{R}\left(A^{-1}\right)\right\} > \alpha,$$

$$\Leftrightarrow$$

$$\alpha^{2} \left\|A\left(\mathbf{x} - \mathbf{x}^{(k)}\right)\right\|_{2}^{2} < \alpha \left(\mathbf{x} - \mathbf{x}^{(k)}\right)^{T} A\left(\mathbf{x} - \mathbf{x}^{(k)}\right).$$

Applying this estimate to the last term of (4.2) gives

$$\begin{aligned} \left\| \mathbf{x} - \mathbf{x}^{(k+1)} \right\|_{2}^{2} &\leq \left\| \mathbf{x} - \mathbf{x}^{(k)} \right\|_{2}^{2} - \alpha \left(\mathbf{x} - \mathbf{x}^{(k)} \right)^{T} A \left(\mathbf{x} - \mathbf{x}^{(k)} \right) \\ &= \left\| \mathbf{x} - \mathbf{x}^{(k)} \right\|_{2}^{2} \left(1 - \alpha \frac{\left(\mathbf{x} - \mathbf{x}^{(k)} \right)^{T} A \left(\mathbf{x} - \mathbf{x}^{(k)} \right)}{\left\| \mathbf{x} - \mathbf{x}^{(k)} \right\|_{2}^{2}} \right). \end{aligned}$$
(4.3)

Since $\mathcal{R}(A)$ is compact, there is a $\varepsilon > 0$ such that $\operatorname{Re}(\lambda) \ge \varepsilon$ for all $\lambda \in \mathcal{R}(A)$ (there is no sequence that can converge to the imaginary axis). Hence

$$\frac{\left(\mathbf{x} - \mathbf{x}^{(k)}\right)^T A\left(\mathbf{x} - \mathbf{x}^{(k)}\right)}{\|\mathbf{x} - \mathbf{x}^{(k)}\|_2^2} \ge \varepsilon.$$

Choose ε such that $\alpha \varepsilon \leq 1$, then it follows from (4.3) that

$$\left\|\mathbf{x} - \mathbf{x}^{(k+1)}\right\|_{2}^{2} \leq \left\|\mathbf{x} - \mathbf{x}^{(k)}\right\|_{2}^{2} (1 - \alpha\varepsilon) =: q^{2} \left\|\mathbf{x} - \mathbf{x}^{(k)}\right\|_{2}^{2}$$

with 0 < q < 1 independent of k. One obtains by induction

$$\left\|\mathbf{x} - \mathbf{x}^{(k)}\right\|_{2} \le q^{k} \left\|\mathbf{x} - \mathbf{x}^{(0)}\right\|_{2}$$

such that $\mathbf{x}^{(k)} \to \mathbf{x}$ as $k \to \infty$.

Remark 4.6 Choice of α for s.p.d. matrices. Let A be symmetric and positive definite. Using Rayleigh's coefficient (2.3), one gets

$$\frac{\operatorname{Re}\left(\mathbf{y}^{*}A^{-1}\mathbf{y}\right)}{\|\mathbf{y}\|_{2}^{2}} = \frac{1}{\|\mathbf{y}\|_{2}^{2}} \left(\left(\operatorname{Re}\left(\mathbf{y}\right)\right)^{T}A^{-1}\operatorname{Re}\left(\mathbf{y}\right) + \left(\operatorname{Im}\left(\mathbf{y}\right)\right)^{T}A^{-1}\operatorname{Im}\left(\mathbf{y}\right) \right) \\
= \frac{1}{\|\mathbf{y}\|_{2}^{2}} \left(\left\|\operatorname{Re}\left(\mathbf{y}\right)\right\|_{2}^{2} \frac{\left(\operatorname{Re}\left(\mathbf{y}\right)\right)^{T}A^{-1}\operatorname{Re}\left(\mathbf{y}\right)}{\left\|\operatorname{Re}\left(\mathbf{y}\right)\right\|_{2}^{2}} + \left\|\operatorname{Im}\left(\mathbf{y}\right)\right\|_{2}^{2} \frac{\left(\operatorname{Im}\left(\mathbf{y}\right)\right)^{T}A^{-1}\operatorname{Im}\left(\mathbf{y}\right)}{\left\|\operatorname{Im}\left(\mathbf{y}\right)\right\|_{2}^{2}} \right) \\
\geq \frac{1}{\|\mathbf{y}\|_{2}^{2}} \left(\left\|\operatorname{Re}\left(\mathbf{y}\right)\right\|_{2}^{2} \lambda_{\min}\left(A^{-1}\right) + \left\|\operatorname{Im}\left(\mathbf{y}\right)\right\|_{2}^{2} \lambda_{\min}\left(A^{-1}\right) \right) \\
= \lambda_{\min}\left(A^{-1}\right) = \frac{1}{\lambda_{\max}\left(A\right)} = \frac{1}{\rho\left(A\right)}.$$

That means, the choice $\alpha < 1/\rho(A)$ guarantees the convergence of the Richardson method.

Remark 4.7 Residual minimization for choosing α_k . One possibility to choose α_k in practice consists in the minimization of the norm of the residual

$$\begin{aligned} \left\| \mathbf{r}^{(k+1)} \right\|_{2}^{2} &= \left\| \mathbf{b} - A \mathbf{x}^{(k+1)} \right\|_{2}^{2} = \left\| \mathbf{b} - A \mathbf{x}^{(k)} - \alpha_{k} A \mathbf{r}^{(k)} \right\|_{2}^{2} = \left\| \mathbf{r}^{(k)} - \alpha_{k} A \mathbf{r}^{(k)} \right\|_{2}^{2} \\ &= \left\| \mathbf{r}^{(k)} \right\|_{2}^{2} - 2\alpha_{k} \mathbf{r}^{(k)^{T}} A r^{(k)} + \alpha_{k}^{2} \left\| A \mathbf{r}^{(k)} \right\|_{2}^{2}. \end{aligned}$$

The necessary condition for a minimum

$$\frac{d}{d\alpha_k} \left\| \mathbf{r}^{(k+1)} \right\|_2^2 = 0$$

gives

$$\alpha_k = \frac{\mathbf{r}^{(k)T} A \mathbf{r}^{(k)}}{\left\| A \mathbf{r}^{(k)} \right\|_2^2}.$$
(4.4)

Since

$$\frac{d^2}{d\alpha_k^2} \left\| \mathbf{r}^{(k+1)} \right\|_2^2 = 2 \left\| A \mathbf{r}^{(k)} \right\|_2^2 > 0,$$

if $\mathbf{r}^{(k)} \neq \mathbf{0}$, one obtains in fact a minimum.

Remark 4.8 Spaces spanned by the iterates. It is by (4.1)

$$\begin{aligned} \mathbf{x}^{(1)} &\in \mathbf{x}^{(0)} + \operatorname{span} \left\{ \mathbf{r}^{(0)} \right\}, \\ \mathbf{x}^{(2)} &\in \mathbf{x}^{(1)} + \operatorname{span} \left\{ \mathbf{r}^{(1)} \right\} \in \mathbf{x}^{(0)} + \operatorname{span} \left\{ \mathbf{r}^{(0)}, \mathbf{r}^{(1)} \right\}. \end{aligned}$$

It holds

$$\mathbf{r}^{(1)} = \mathbf{b} - A\mathbf{x}^{(1)} = \mathbf{b} - A\mathbf{x}^{(0)} - \alpha_0 A\mathbf{r}^{(0)} = \mathbf{r}^{(0)} - \alpha_0 A\mathbf{r}^{(0)}$$

and consequently

$$\mathbf{x}^{(2)} \in \mathbf{x}^{(0)} + \operatorname{span}\left\{\mathbf{r}^{(0)}, A\mathbf{r}^{(0)}\right\}.$$

One obtains by induction

$$\mathbf{x}^{(k)} \in \mathbf{x}^{(0)} + \operatorname{span}\left\{\mathbf{r}^{(0)}, A\mathbf{r}^{(0)}, \dots, A^{k-1}\mathbf{r}^{(0)}\right\}.$$

Definition 4.9 Krylov subspace. Let $\mathbf{q} \in \mathbb{R}^n$ and $A \in \mathbb{R}^{n \times n}$. Then, the space

$$K_m(\mathbf{q}, A) := \operatorname{span}\left\{\mathbf{q}, A\mathbf{q}, \dots, A^{k-1}\mathbf{q}\right\}$$

is called the Krylov² subspace of order m which is spanned by **q** and A.

Remark 4.10 Next goal. It holds $\mathbf{x}^{(k)} \in \mathbf{x}^{(0)} + K_k(\mathbf{r}^{(0)}, A)$. In the following, Richardson's method will be generalized by constructing the iterates $\mathbf{x}^{(k)}$ in this manifold with respect to certain optimality criteria.

²Krylov